## APPROXIMATE METHOD OF SOLUTION OF DYNAMIC PROBLEMS FOR LINEAR VISCOELASTIC MEDIA

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An approximate method of solution of dynamic problems for linear viscoelastic media exhibiting an instantaneous elasticity, is given. The method yields exact results for media which satisfy the Maxwell model. In the past the investigations were focused mainly on the simplest problems with the kernels of viscoelastic operators assuming particular forms, especially for the Maxwell body or in the neighborhood of a viscoelastic wavefront [1-3], and on the asymptotic solutions using the method of steepest descent [4].

1. Formulation of the problem and a method of approximate solution. Linear viscoelastic bodies exhibiting instantaneous elasticity are described by two linear, time-dependent Boltzmann -type operators $L(\zeta)$ and $M(\zeta)$

$$
\begin{align*}
& L(\xi)=\lambda\left[\zeta(t)-\int_{0}^{1} f_{1}(t-\xi) \zeta(\xi) d \xi\right]  \tag{1.1}\\
& M(\zeta)=\mu\left[\zeta(t)-\int_{0}^{1} f_{2}(t-\xi) \zeta(\xi) d \xi\right]
\end{align*}
$$

where $f_{1}(t)$ and $f_{2}(t)$ are kemels of the viscoelastic operators which are approximated more conveniently by expressing them in the form of a sum of exponential terms, i. e. [5]

$$
\begin{equation*}
f_{j}(t)=\sum_{m=1}^{n} \frac{\gamma_{m j}}{\tau_{m}} \exp \left(-\frac{t}{\tau_{m}}\right), \quad \sum_{m=1}^{n} \gamma_{m j}=1 \tag{1.2}
\end{equation*}
$$

$\lambda$ and $\mu$ are elastic constants, $\gamma_{m j}$ are the viscosity parameters and $\tau_{m}$ denote the relaxation times.

We shall limit ourselves, for simplicity, to considering two-dimensional plane problems, and reduce the equations of motion of a linear, isotropic, viscoelastic medium, to the form

$$
\begin{align*}
& L_{j}\left(\Delta u_{j}\right)=\frac{1}{a_{j}{ }^{2}} \frac{\hat{\partial}^{2} u_{j}}{\partial t^{2}}, \quad L_{j}\left(\Delta v_{j}\right)=\frac{1}{a_{j}{ }^{2}} \frac{\partial^{2} v_{j}}{\partial t^{2}}, \quad j=1,2  \tag{1.3}\\
& L_{1}(\zeta)=\frac{1}{1+2 \mu}[L(\zeta)+2 M(\zeta)], \quad L_{2}(\zeta)=\frac{1}{\mu} M(\zeta)
\end{align*}
$$

where the functions $u_{j}$ and $v_{j}$ must satisfy the following additional relations:

$$
\frac{\partial u_{1}}{\partial y}=\frac{\partial v_{1}}{\partial x}, \quad \frac{\partial u_{2}}{\partial x}=-\frac{\partial v_{2}}{\partial y}, \quad a_{1}{ }^{2}=\frac{\lambda+2 \mu}{\rho}, \quad a_{2}{ }^{2}=\frac{\mu}{\rho}
$$

When the Poisson's ratio is constant, which is true to within a large degree of accuracy, the kemels $f_{1}(t)$ and $f_{2}(t)$ become equal to each other.

To elucidate the approximate method, we consider an arbitrary integro-differential equation

$$
L(\Delta u)=\frac{1}{c^{2}} \frac{\partial^{2} u}{\partial t^{2}}
$$

of the type (1.3), and apply to it a Laplace transform in $t$. In the case of zero initial conditions, which is not essential in the present approach, we obtain the following equation for $u_{0}(x, y, p)$ :

$$
\begin{aligned}
& \Delta u_{0}=\frac{Q^{2}(p)}{t^{2}} u_{0}, \quad Q^{2}(p)=p^{2}\left[1-f_{0}(p)\right]^{-1} \\
& f_{0}(p)=\int_{0}^{\infty} f(t) \exp (-p t) d t
\end{aligned}
$$

where $c$ denotes any one of the velocities $a_{j}$. The quantity $Q^{2}(p)$ is written for the kernel $f(t)$ of the form (1.2) in the following manner:

$$
\begin{align*}
& Q^{2}(p)=p^{2}+c_{1} p-c_{2}+c_{2} Q_{1}(p)  \tag{1.4}\\
& c_{1}=\sum_{m=1}^{n} \frac{\gamma_{m}}{\tau_{m}}, \quad c_{2}=\sum_{m=1}^{n} \sum_{l=1+m}^{n} \gamma_{m} \gamma_{l}\left(\frac{1}{\tau_{m}}-\frac{1}{\tau_{l}}\right)^{2} \\
& \left|Q_{\mathrm{I}}(p)\right| \leqslant\left|\frac{1}{1+p \tau_{1}}\right|
\end{align*}
$$

In the case of a Maxwellian material we have a single relaxation time, and the quantity $Q^{2}(p)$ simplifies to

$$
\begin{equation*}
Q^{2}(p)=p^{2}+p / \tau_{1} \tag{1.5}
\end{equation*}
$$

Let us make the following assumption. Since in many dynamic problems for linear viscoelastic media the time taken by the wave processes is much shorter thian the shortest relaxation time $\tau_{1}$, it follows that for the time intervals in question,which is $t$, we can neglect the last term in (1.4) (for a Maxwellian body this term will be identically equal to zero).
2. One-dimensional plane wave in a viscoelastic medium . Let us consider the simplest problem of propagation of a plane wave in a half-space $y>0$, the wave generated by a normal presure applied at the boundary $y=0$ of this half-space. The problem reduces to that of solving the equation

$$
L_{\mathrm{I}}\left(\frac{\partial^{2} v}{\partial y^{2}}\right)=\frac{1}{a^{2}} \frac{\partial^{2} v}{\partial t^{2}}, \quad a_{\mathrm{I}}=a
$$

for the displacement $v$, satisfying the following boundary and initial conditions:

$$
\begin{aligned}
& \sigma_{v u}=-F(t) \quad(y=0), \quad v=0, \quad(y=\infty) \\
& v=\partial v / \partial t=0 \quad(t=0)
\end{aligned}
$$

Applying now the Laplace transformation in $t$, we obtain a problem the solution of which has the form

$$
\begin{equation*}
v_{0}(y, p)=\frac{Q(p)}{\rho a p} F_{0}(p) \exp \left[-Q(p) \frac{y}{a}\right] \tag{2.1}
\end{equation*}
$$

Solving (2.1) for $p$, in which case the quantity $Q^{2}(p)$ is given by the formula(1.4) with the last term omitted, we obtain the following expressions for the displacement $v$ and stress $\sigma_{y y}$ :

$$
\begin{aligned}
& v(y, t)=\frac{1}{\rho a} \int_{y / a}^{t} F(t-\xi)\left[\exp \left(-\frac{c_{1} \xi}{2}\right) I_{0}\left(c_{0} \sqrt{\xi^{2}-\frac{y^{2}}{a^{2}}}\right)+\right. \\
& \left.c_{0} \int_{y / a}^{\xi} \exp \left(-\frac{c_{1} \eta}{2}\right) I_{0}\left(c_{0} \sqrt{\eta^{2}-\frac{y^{2}}{a^{2}}}\right) d \eta\right] d \xi \\
& c_{0}=\sqrt{\frac{c_{1}^{2}}{4}+c_{2}} \\
& \sigma_{y y}(y, t)=-\exp \left(-\frac{c_{2} y}{2 a}\right) F\left(t-\frac{y}{a}\right)+\frac{c_{0} y}{a} \int_{v / a}^{t} F(t-\xi) \times \\
& \quad \exp \left(-\frac{c_{1} \xi}{2}\right)\left(\xi^{2}-\frac{y^{2}}{a^{2}}\right)^{-1 / 2} I_{1}\left(c_{0} \sqrt{\xi^{2}-\frac{y^{2}}{a^{2}}}\right) d \xi
\end{aligned}
$$

For the Maxwellian body this yields an exact solution which was already constructed in [1] using the correspondence principle, while in the case of an elastic body where $f(t)=0$, we obtain a known solution for the propagation of a plane wave through an elastic medium. An approximate relation connecting the stress with the velocity of the particles behind the wave front is also easily obtained

$$
\sigma_{y y}(y, t)=-\rho a\left\{\frac{d v}{d t}+\int_{y / a}^{t} \frac{d v}{\partial \xi} \frac{\partial}{d \xi}\left[\exp \left(-\frac{c_{1} \xi}{2}\right) I_{0}\left(c_{0} \xi\right)\right] d \xi\right\}
$$

and it represents a well known relation for a plane, elastic wave.


Fig. 1


Fig. 2

Fig. 1 depicts the dependence of the magnitude of the stress $\sigma_{y y}$ at two points and the dependencies on $t$, for the following initial values of the problem:

$$
\begin{aligned}
& F(t)=\sigma_{0} \sin ^{2}\left(\pi t / t_{1}\right) \quad\left(0 \leqslant t \leqslant t_{1}\right), \quad n=3, \quad \gamma_{1}=0.6 \\
& \gamma_{2}=0.3, \gamma_{3}=0.1, \quad \tau_{1}=10^{5} \mu \mathrm{~s}, \quad \tau_{2}=10^{7} \mu \mathrm{~s}, \\
& \tau_{3}=10^{7} \mu \mathrm{~s}
\end{aligned}
$$

with the dashed line corresponding to the elastic problem. Other one-dimensional problems of propagation of plane waves can be solved in an analogous manner.
3. Approximate solution of the Lamb's problem. The problem is reduced to that of solving the equations (1.3) for a half-plane $y<0$, uner the following boundary and initial conditions:

$$
\begin{aligned}
& \sigma_{y y}=\sigma_{0} \delta(x) \delta(t), \quad \sigma_{x y}=\sigma_{\mathrm{x}} \delta(x) \delta(t) \quad(y=0) \\
& u_{j}=v_{j}=0 \quad\left(\sqrt{x^{2}+y^{2}}=\infty\right) \\
& u_{j}=v_{j}=\partial u_{j} / \partial t=\partial v_{j} / \partial t=0 \quad(t=0)
\end{aligned}
$$

Assuming that the Poisson's ratio is constant, we apply to the problem the Laplace transform in $t$ and the Fourier transform in $x$. Then for the functions

$$
\begin{aligned}
& \bar{u}_{j 0}=\int_{-\infty}^{\infty} d x \int_{0}^{\infty} u_{j} \exp (i \omega x-p t) d t \\
& \bar{v}_{j 0}=\int_{-\infty}^{\infty} d x \int_{0}^{\infty} v_{j} \exp (i \omega x-p t) d t
\end{aligned}
$$

we obtain

$$
\begin{align*}
& \bar{u}_{\mathrm{I} 0}=A_{\mathrm{I}} \exp \left[y R_{\mathrm{I}}(p)\right], \quad \bar{v}_{20}=A_{2} \exp \left[y R_{2}(p)\right]  \tag{3.1}\\
& \bar{u}_{20}=-i \omega^{-1} R_{2}(p) \bar{v}_{20}, \quad \bar{v}_{\mathrm{I} 0}=i \omega^{-1} R_{\mathrm{I}}(p) \bar{u}_{\mathrm{I} 0} \\
& R_{j}(p)=\left[\omega^{2}+Q^{2}(p) / a_{j}^{2}\right]^{1 / 2}, \quad A_{j}=\Delta_{j} / \Delta, \quad j=1,2 \\
& \Delta=\left[\left(2 \omega^{2} a_{2}^{2}+Q^{2}(p)\right)^{2}-4 \omega^{2} a_{2}^{4} R_{\mathrm{I}}(p) R_{\mathrm{I}}(p)\right] \\
& \Delta_{\mathrm{I}}=-\frac{\omega Q^{2}(p)}{\rho p^{2} a_{2}^{2}}\left[i \sigma_{0}\left(2 \omega^{2} a_{2}^{2}+Q^{2}(p)\right)+2 \omega^{2} a_{2}^{2} \sigma_{\mathrm{I}} R_{2}(p)\right] \\
& \Delta_{2}=-\frac{\omega Q^{2}(p)}{\rho p^{2} a_{2}^{2}}\left[2 \omega^{2} a_{2}{ }^{2} \sigma_{0} R_{\mathrm{I}}(p)-i \sigma_{I}\left(2 \omega^{2} a_{2}^{2}+Q^{2}(p)\right)\right]
\end{align*}
$$

Let us inspect the values of the stresses. Using the solution in the form (3.1), we obtain the following expressions for the Laplace and Fourier transforms of the stresses $\sigma_{i j}{ }^{0}$ :

$$
\begin{align*}
& \sigma_{i j}^{(0)}=Q(p) \sum_{k=1}^{2} \int_{-\infty}^{\infty} P_{i j}^{(k)}(s) \exp \left[Q(p)\left(y R_{j 0}(s)-i s x\right)\right] d s  \tag{3.2}\\
& P_{x x}^{(1)}=-i \frac{\Delta_{10}}{\Delta_{0}}\left[a_{1}{ }^{2} s^{2}-\left(a_{1}^{2}-2 a_{2}^{2}\right) R_{10}{ }^{2}(s)\right], \quad P_{x x}^{(2)}=-P_{y y}^{(2)} \\
& P_{x x}^{(2)}=-2 s \frac{\Delta_{20}}{\Delta_{0}} R_{20}, \quad P_{y u}^{(1)}=-i \frac{\Delta_{10}}{\Delta_{0}}\left[s^{2}\left(a_{1}^{2}-2 a_{2}^{2}\right)-\right. \\
& \left.\quad a_{1}{ }^{2} R_{10}{ }^{2}(s)\right] \\
& P_{x y]}^{(1)}=2 s a_{2}{ }^{2} \frac{\Delta_{10}}{\Delta_{0}} R_{10}(s), \quad P_{x y}^{(2)}=-i \frac{\Delta_{20}}{\Delta_{0}} R_{0}(s) \\
& R_{j 0}(s)=\sqrt{s^{2}+a_{j}^{-2}}, \quad R_{0}(s)=\left(1+2 s^{2} a_{2}{ }^{2}\right) \\
& \Delta_{0}=\left[R_{0}^{2}(s)-4 s^{2} a_{2}^{4} R_{10}(s) R_{20}(s)\right] \\
& \Delta_{10}=-\left[i \sigma_{0} R_{0}(s)+2 s a_{2}{ }^{2} \sigma_{1} R_{20}(s)\right] \\
& \Delta_{20}=-\left[2 s a_{2}{ }^{2} \sigma_{0} R_{10}(s)-i \sigma_{1} R_{0}(s)\right]
\end{align*}
$$

To analyze the expressions (3.2), we pass to the complex $s$-plane and replace the integration with respect to $s$ by integration along the contours $\Gamma_{1}, \Gamma_{2}$ and $\Delta \Gamma$, as shown in Fig. 2. The branch points and poles of the integrand functions are given by

$$
\begin{aligned}
& \operatorname{Re} s_{1}=0, \quad \operatorname{Re} s_{2}=0, \quad \operatorname{Im} s_{1}=a_{1}^{-1}, \quad \operatorname{Im} s_{2}=a_{2}^{-1} \\
& \operatorname{Re} s_{R}=0, \quad \operatorname{Im} s_{R}=a_{R}^{-1},\left.\quad \Delta_{0}(s)\right|_{s=e_{R}}=0
\end{aligned}
$$

Using the method given in [6] and computing the quadratures in (3.2) along the contours $\Gamma_{1}, \Gamma_{2}$ and $\Delta \Gamma$ with the help of the Jordan lemma and theory of residues, we can obtain the expressions for the stresses $\sigma_{i j}{ }^{(0)}$ in the half-plane $y \leqslant 0$. For example, we obtain the following expression for $\sigma_{x x}^{(0)}$ at the free boundary $y=0$, for $\sigma_{1}=0$ :

$$
\begin{align*}
& \sigma_{x x}^{(0)}=Q(p)\left\{\left[P_{x x}^{(1)}+P_{x x}^{(2)}\right]\left(s-i a_{R}^{-1}\right) \exp [i|x| s Q(p)]\right\}_{-1 a_{R}^{-1}+}^{a_{1}}+  \tag{3.3}\\
& \quad Q(p) \int_{a_{2}^{-1}}^{a_{0}^{-1}} \sigma_{0}\left[\frac{F_{1}(i \eta)}{\Delta_{0}(i \eta)}+\frac{F_{2}(i \eta)}{\bar{\Delta}_{0}(i \eta)}\right] \exp [-\eta|x| Q(p)] d \eta \\
& \bar{\Delta}_{0}(s)=\left[R_{0}^{2}(s)+4 s^{2} a_{2}^{4} R_{10}(s) R_{20}(s)\right] \\
& F_{1,2}(s)=4 s^{2} R_{10}(s) R_{20}(s) \mp\left(2 s^{2}+a_{2}^{-2}\right)\left[2 s^{2}-a_{2}^{-2}\left(1-2 a_{2}^{2} / a_{1}^{2}\right)\right]
\end{align*}
$$

The above expression was derived incorrectly in a similariy formulated problem in [7].
In order to invert the expression (3.3) with respect to $p$, we must invert

$$
Q(p) \exp [-\alpha Q(p)]
$$

and this is easily done for the quantity $Q^{2}(p)$ defined by (1.4). We obtain

$$
\begin{aligned}
& \frac{1}{2 \pi i} \int_{\alpha_{0}-i \infty}^{\alpha_{0}+i \infty} Q(p) \exp [-\alpha Q(p)+p t] d p= \\
& \exp \left(-1 / 2 c_{1} t\right)\left(\delta^{\prime}(t-\alpha) I_{0}\left(c_{0} \sqrt{t^{2}-\alpha^{2}}\right)-\right. \\
& 2 \delta(t-\alpha)\left(t^{2}-\alpha^{2}\right)^{-1 / 2} I_{1}\left(c_{0} \sqrt{t^{2}-\alpha^{2}}\right)+ \\
& c_{0}\left[\left[\left(t^{2}-\alpha^{2}\right)^{-1 / 2}-1 / 2 \alpha^{2}\left(t^{2}-\alpha^{2}\right)^{-2 / 2}\right] I_{1}\left(c_{0} \sqrt{t^{2}-\alpha^{2}}\right)+\right. \\
& \left.\left.c_{0}^{2} \alpha^{2}\left(t^{2}-\alpha^{2}\right)^{-1 / 2} I_{\mathrm{I}}^{\prime}\left(c_{0} \sqrt{t^{2}-\alpha^{2}}\right)\right] H(t-\alpha)\right\}
\end{aligned}
$$

For a viscoelastic half-plane made of material conforming to the Maxwell's model, the formula (3.3) yields an exact expression for $\sigma_{x x}^{(0)}$ at the boundary $y=0$.

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